

A presentation of the fundamental biquandle of the n-twist spun trefoil

Sosuke Ashihara

Hiroshima University

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$$\{ \text{quandles} \} \subset \{ \text{biquandles} \}$$

A classical link \rightarrow The fundamental quandle
(a complete invariant)

A surface link \rightarrow The fundamental quandle
(not a complete invariant)

\rightarrow The fundamental biquandle



a stronger invariant ?

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Definition (biquandle)

A **biquandle** is a set B with four binary operations $(a, b) \mapsto a^b, a_b, a^{\bar{b}}$ and $a_{\bar{b}}$ which satisfy the following axioms:

1. $\forall b \in B$, each maps $a \mapsto a^b, a_b, a^{\bar{b}}$ and $a_{\bar{b}}$ are bijections taking $a \in B$ into B .
2. $\forall a, x, y \in B$,
 $x = a_x \Leftrightarrow a = x^a, \quad y = a^{\bar{y}} \Leftrightarrow a = y_{\bar{a}}$.
3. $\forall a, b \in B$,
 $a = a^{b\bar{b}_a}, b = b_{a\bar{a}^b}, a = a^{\bar{b}b_{\bar{a}}}, b = b_{\bar{a}a^{\bar{b}}}$.
4. $\forall a, b, c \in B$,
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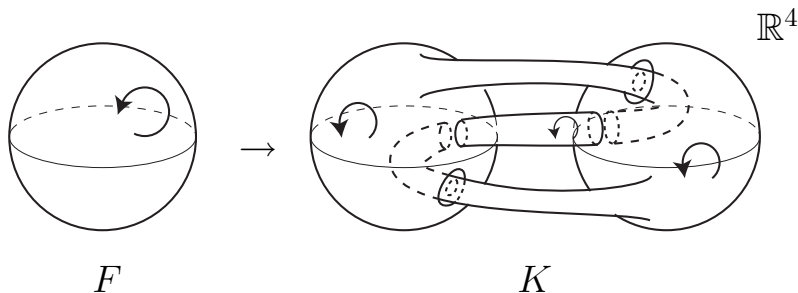
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Introduction

Definition (surface link)

A **surface link** K is the image of an embedding of a closed oriented surface F into \mathbb{R}^4 .



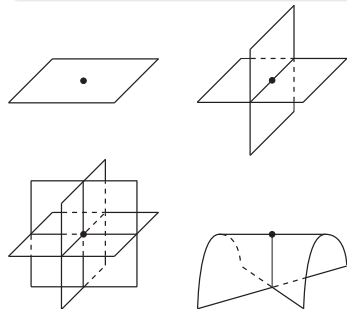
Introduction

Definition (surface diagram)

K : a surface link.

$p : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ a generic projection.

A *surface diagram of K* is $p(K)$ with height information.



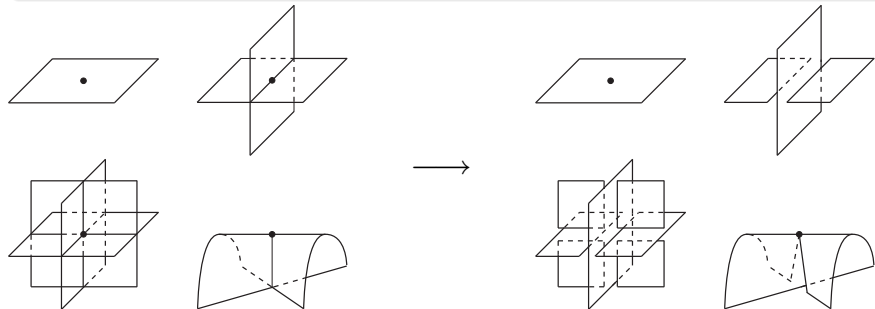
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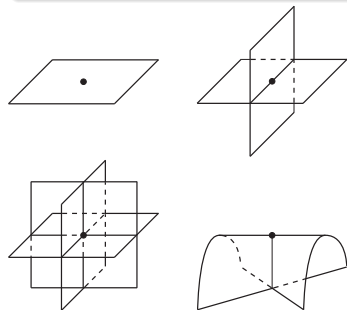
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Definition (semi-sheet of a surface diagram)

D : a surface diagram.

Σ : the double curves of D .

We call connected components of $D \setminus N(\Sigma)$ *semi-sheets* of D .



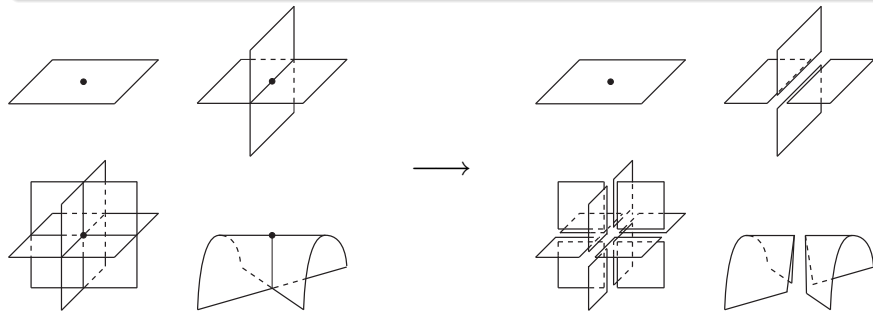
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K : a surface link. \rightarrow $BQ(K)$: the fundamental biquandle of K .

\downarrow \updownarrow def

D : a surface diagram. \rightarrow $BQ(D)$: the fundamental biquandle of D .

Theorem (Carrell'09)

The definition of $BQ(K)$ is well-defined.

The biquandle $BQ(K)$ is an invariant of K .

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Theorem (Carrell'09)

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Definition (ch-diagram)

Γ : a singular link diagram with some markers.

We call Γ a *ch-diagram*.

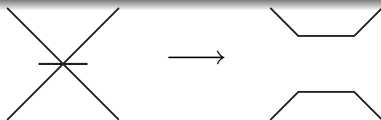


Figure: examples of ch-diagrams

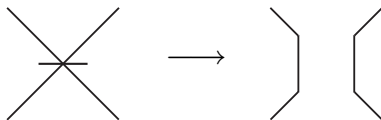
A ch-diagram with a certain condition represents a surface link.

Definition (adequate ch-diagram)

A *ch-diagram* is **adequate** if a diagram of the unlink results when all marked vertices are consistently A- or B-smoothed.



A-smoothing



B-smoothing

Definition (surface link constructed by a ch-diagram)

Γ : *an adequate ch-diagram.*

$F(\Gamma) \subset \mathbb{R}^4$: *the surface link constructed as follows:*



Γ

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$\longrightarrow t = 0$



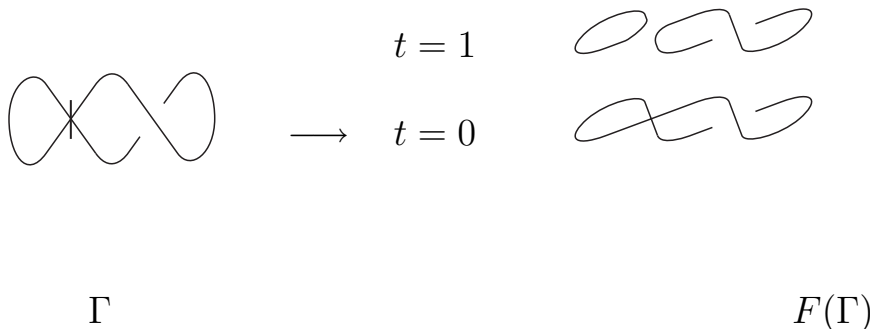
Γ

$F(\Gamma)$

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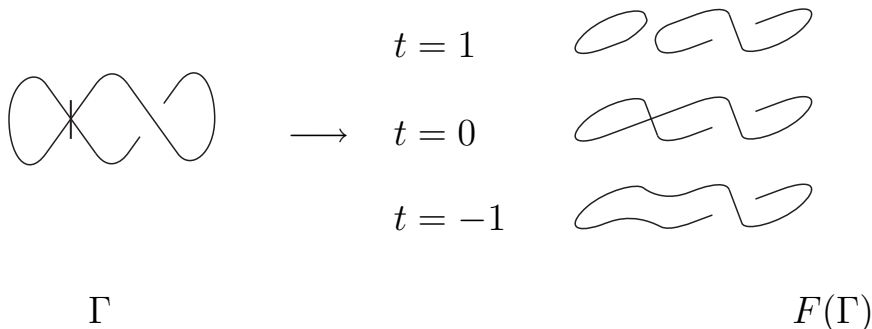
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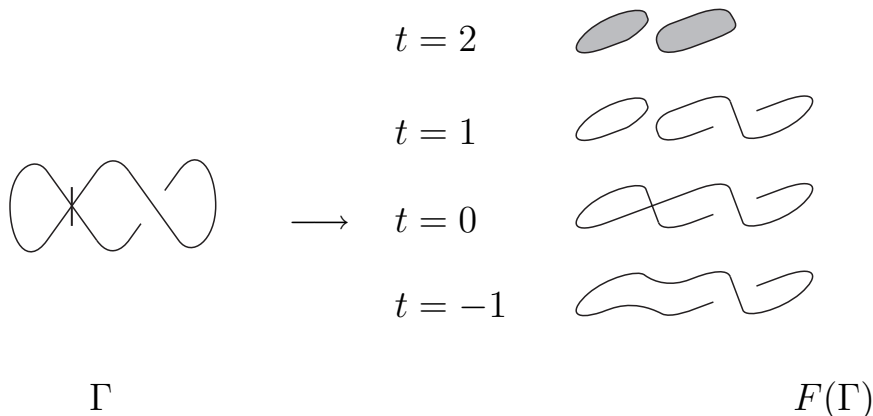
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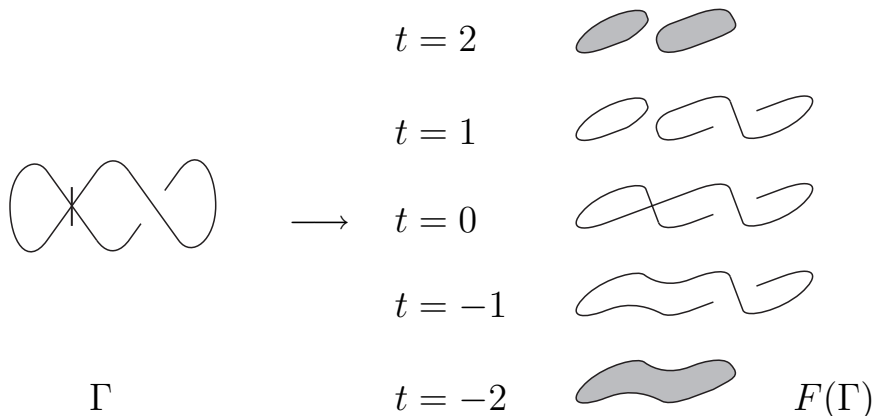
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Definition (ch-diagram of a surface link)

K : a surface link.

An adequate *ch*-diagram Γ is a *ch-diagram of K* if $F(\Gamma) \cong K$ in \mathbb{R}^4 .

Theorem (Yoshikawa'94)

Any surface link K has a *ch-diagram of K* .

Definition and Theorem

Γ : an oriented adequate. $\rightarrow BQ(\Gamma)$: the fundamental biquandle of Γ .

\downarrow
 $F(\Gamma)$: the surface.
associated to Γ

$\updownarrow \cong$
 K : a surface link. $\rightarrow BQ(K)$

Theorem (A.)

K : a surface link.

Γ : a ch-diagram of K .

Then $BQ(K) \cong BQ(\Gamma)$.

Definition and Theorem

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The spun trefoil

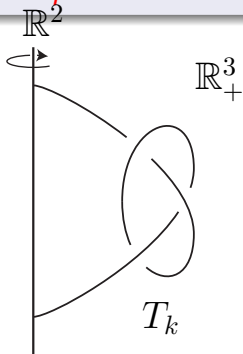
Definition (spun knot)

$\mathbb{R}_+^3 := \{(x_1, x_2, x_3, x_4) \mid x_3 \geq 0, x_4 = 0\}$.

k : a classical knot.

$T_k \subset \mathbb{R}_+^3$: a tangle of k whose end points lie in \mathbb{R}^2 .

Then $\{(x_1, x_2, x_3 \sin \theta, x_3 \cos \theta) \mid (x_1, x_2, x_3) \in T_k, \theta \in [0, 2\pi)\}$ forms a surface knot. We call it **the spun k** .



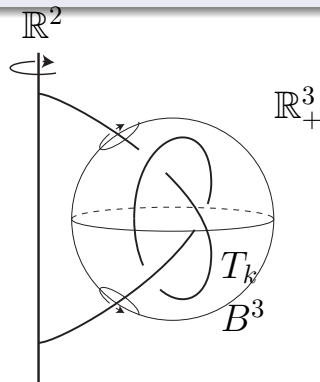
The twist-spun trefoil

Definition (twist-spun knot)

While rotating \mathbb{R}_+^3 about \mathbb{R}^2 , twist B^3 n -times ($n \in \mathbb{Z}$).

Then we have another surface knot.

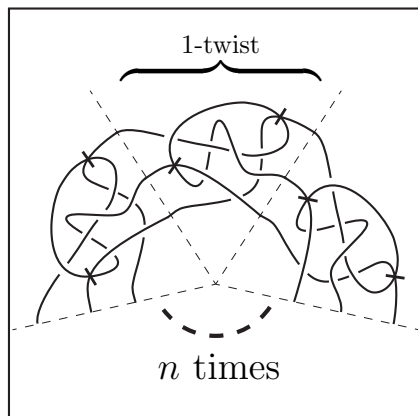
We call it *the n -twist-spun k* .



The twist-spun trefoil

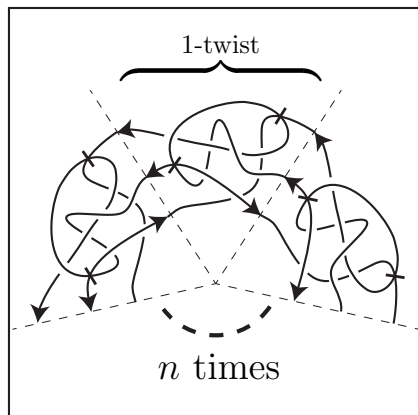
Theorem (Inoue)

The following ch-diagram represents the n -twist-spun trefoil.



Main Theorem

$\tau^n T$: the oriented ch-diagram as illustrated in below,
then we have the following result.



Main Theorem

$$\phi_1(a, b, c) = (b^{\bar{b}^{-1}})_a$$

$$\phi_2(a, b, c) = b^{\bar{b}^{-1} \bar{c}^b}$$

$$\phi_3(a, b, c) = b_c$$

$$r(a, b, c) : a^{b^{\bar{b}^{-1}}} = (c^b)_{\bar{b}^{-1}}$$

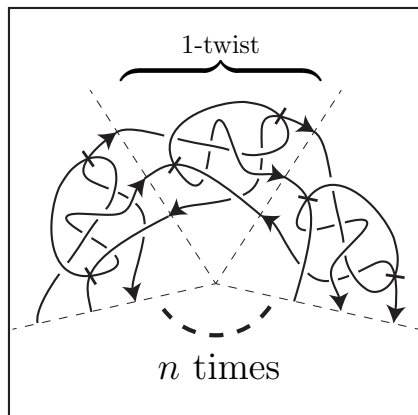
Theorem (A.)

$$BQ(\tau^n T)$$

$$= \langle a_1, b_1, c_1, \dots, a_n, b_n, c_n \mid a_{i+1} = \phi_1(a_i, b_i, c_i), b_{i+1} = \phi_2(a_i, b_i, c_i), c_{i+1} = \phi_3(a_i, b_i, c_i), r(a_i, b_i, c_i), a_1 = \phi_1(a_n, b_n, c_n), b_1 = \phi_2(a_n, b_n, c_n), c_1 = \phi_3(a_n, b_n, c_n) \rangle.$$

Main Theorem

$-\tau^n T$: the orientation reversed $\tau^n T$,
then we have the following result.



Main Theorem

$$\psi_1(a, b, c) = (b^{b^{-1}})_{\bar{a}}$$

$$\psi_2(a, b, c) = b^{b^{-1}}c^{\bar{b}}$$

$$\psi_3(a, b, c) = b_{\bar{c}}$$

$$r'(a, b, c) : a^{\overline{b^{b^{-1}}}} = (c^{\bar{b}})_{b^{b^{-1}}}$$

Theorem (A.)

$$BQ(-\tau^n T)$$

$$= \langle a_1, b_1, c_1, \dots, a_n, b_n, c_n \mid a_{i+1} = \psi_1(a_i, b_i, c_i), b_{i+1} = \psi_2(a_i, b_i, c_i), c_{i+1} = \psi_3(a_i, b_i, c_i), r'(a_i, b_i, c_i), a_1 = \psi_1(a_n, b_n, c_n), b_1 = \psi_2(a_n, b_n, c_n), c_1 = \psi_3(a_n, b_n, c_n) \rangle.$$

Thank you!